## **Abbreviations**

2D 2-dimensional 3D 3-dimensional **AMLPP** Approximate minimum-length pseudo-polygon; see Page 273 CAV Cavity; see Page 102 CH Convex hull; see Page 101 **ESP** Euclidean shortest path; see Page 19 iff Read: if and only if; see Page 14 MLA Minimum-length arc; see Page 276 MLP Minimum-length polygon; see Page 118, 229-231, 301 **MLPP** Minimum-length pseudo-polygon; see Page 273 MPP Minimum-perimeter polygon; see Page 115 **RBA** Rubberband algorithm; see Page 63 **RCH** Relative convex hull; see Page 120 SPM Shortest path map; see Page 161 **SRP** Safari route problem; see Page 345 TPP Touring polygon problem; see Page 309 WRP Watchman route problem; see Page 323 ZRP Zookeeper route problem; see Page 345

## **Symbols**

```
|S|
                 Cardinality of set S
                 Relation sign for being parallel
\partial S
                 Frontier of set S
                 Logical 'and'
                 Logical 'or'
                 Intersection of sets
                 Union of sets
\bigcup
                 Straight line segment with endpoints p and q
pq
                 Triangle with vertices p, q, and r
pqr
                 Trapezoid or triangle (in a partitioning)
\triangle
                 Straight line defined by points p and q; orientation "from p to q"
\overline{pq}
                 Angle formed by rotating segment pq clockwise into segment qr
\triangleleft(pqr)
End of a proof or of an example
a,b,c
                 Real numbers
\mathcal{A}(.)
                 Area of a measurable set (as a function)
\alpha, \beta
                 Angles
\mathbb{C}
                 Set of complex numbers a+i\cdot b, with i=\sqrt{-1} and a,b\in\mathbb{R}
                 Minkowski metrics, for m = 1, 2, ... or m = \infty
d_m
d_e
                 Euclidean metric; note that d_e = d_2
D
                 Determinant; see Page 100
δ
                 Real number greater than zero
                 Edge (e.g. of a graph); real constant e = \exp(1) \approx 2.7182818284
E
                 Set of edges of a graph
                 Real number greater than zero (the accuracy of an RBA)
ε
                 Real number greater than zero (a shift distance)
\varepsilon_{s}
                 Functions, for example from \mathbb N into \mathbb R
f,g,h
                 Simple cube-curve
g
                 Tube (i.e., the union of cubes) of a simple cube-curve g
g
                 Face of a polyhedron
```

370 Symbols

```
F
                  Set of faces of a polyhedron
G
                  Graph
                  Set \{..., -2, -1, 0, 1, 2, ...\} of integers
\mathbb{G}
                  Curve in Euclidean space (e.g. straight line, polyline, smooth curve)
γ
Н
                  Half plane; see Page 99
i, j, k, l, m, n
                  Natural numbers
                  Number of iterations, e.g. in a rubberband algorithm
                  Natural number; index of points or vertices in a path
k
                  Natural number; total number of items
                  Function in \varepsilon
κ
L
                  Length (as a real number)
\mathscr{L}(.)
                  Length of a rectifiable curve (as a function)
                  Length of a path \rho
l(\rho)
                  Real number; e.g. between 0 and 1
λ
                  Natural number; e.g. defining the complexity of the input
n
N
                  Neighbourhood (in the Euclidean topology, or in grids)
\mathbb{N}
                  Set \{0,1,2,\ldots\} of natural numbers
                  Asymptotic upper time bound
\mathcal{O}(.)
                  Points in \mathbb{R}^2 or \mathbb{R}^3, with coordinates x_p, y_p, or z_p
p,q
p(x)
                  Polynomial in x
                  x-coordinate of point p or point p_i
p.x, p_i.x
                  y-coordinate of point p or point p_i
p.y, p_i.y
                  z-coordinate of point p or point p_i
p.z, p_i.z
                  Polygon
P^{\bullet}, P^{\circ}
                  Closure and topological interior of polygon P
                  Plane in \mathbb{R}^3; real constant \pi = 4 \times \arctan(1) \approx 3.14159265358979
\pi
П
                  Polyhedron
\Pi^{\bullet}, \Pi^{\circ}
                  Closure and topological interior of polyhedron \Pi
\prod_{i=1}^k S_i
                  Product of sets S_i
P
                  Partitioning (of the plane or of a simple polygon)
                  Radius of a disk or sphere; point in \mathbb{R}^2 or \mathbb{R}^3
\mathbb{R}
                  Set of real numbers
                  Path with finite number of vertices; see Page 19
ρ
                  Point in \mathbb{R}^2 or \mathbb{R}^3
S, S_i
                  Sets
                  Family of sets
S
                  Point in \mathbb{R}^2 or \mathbb{R}^3
T
                  Tree; threshold (a real number)
                  Threshold (real number)
T
                  Trapezoidation or triangulation (of the plane or of a simple polygon)
```

Symbols 371

Vertex or node; a point in  $\mathbb{R}^2$  or  $\mathbb{R}^3$ , with coordinates  $x_v$ ,  $y_v$ , or  $z_v$ 

V Set of vertices of a graph

V(G), V(T) Set of vertices of graph G or tree T

 $V(\rho)$  Set of vertices of a path  $\rho$ 

 $vu, \overline{vu}$  Undirected or directed line segment between points v and u

x Real variable

x Vector

y Real variable

y Vector

 $\mathbb{Z}$  Set of integers

$\pi$ , 16	Melkman, 112, 122, 124, 125
	Mitchell, 161, 162
Abel, H. N., 290	numerical for MLP in cube-curve, 251
accuracy, 20	optimized, 15
global and local, 65	Papadimitriou, 40, 225
accuracy parameter, 43	quickhull, 107
adjacency	recursive MLP, 122
in a graph, 23	rubberband, 63
of cuts, 193	scientific, 12
adjacent	Seidel, 139
4- and 8-, 17	Sklansky, 110
polygonal cuts, 193	straightforward, 105
adjacent to, 255	Thorup, 197
Alexandria, the ancient city of, 20	Toussaint, 119
algorithm, 12	with guaranteed error limit, 236
$\delta$ -approximate, 40	within guaranteed error limits, 40
κ-linear, 14	without guarantee, 40
A <sup>⋆</sup> search, 26	algorithm, exact, 39
approximate, 43, 80	AMLPP, 273
approximate MLP, for cube-curves, 282	angle, 100
approximative, 43	end-, middle-, and inner-, 241
arithmetic, 12, 287	annulus, 98
arithmetic over the rational numbers, 12	ants, 96
art gallery, 308	arc, minimum-length, 276
Bülow-Klette, 235, 254	area, 101
breadth-first search, 23	of a simple polygon, 102
Chazelle, 177	asymptotic time, 13
Dijkstra, 25, 35, 62, 88, 91, 157, 207, 237, 328	attraction, 31, 61
discrete surface ESP, 207	Bülow, T., 231, 234
exact, 40, 80	Babylonian method, 45
for tangent calculation, 328	Bajaj, C., 288
Gisela's, 123	band, 195
Graham, 105	bands, continuous, 195
iterative, 42	Berlekamp, E. R., 288, 290, 292
Klette, 111	Bhowmick, P., 35
Klette-Kovalevsky-Yip, 116	bisection method, 250
J I 7	

Polzono P D I N 45 52	maximal (2.2) 275
Bolzano, B. P. J. N., 45, 53 border, inner and outer, 126	maximal (2,3)-, 275
	maximal 2-, 275
border tracing, 126	simple, 232, 274
Bruckstein, A. M., 61	cube-arc unit, 275
G : G : 20	2- and 3-, 275
Canopic Gate, 20	regular, 275
Cartesian coordinate system, 17	cube-curve, 230
Cartesius, 17	first-class, 231
case, degenerate, 75	simple, 230
Cauchy Convergence Criterion, 45	curve, 19
Cauchy, AL., 45, 56	complete for tube, 231
CAV, 102	Jordan, 28
cavity, 98	polygonal, 19
of a simple polygon, 102	simple, 28
cell, 81, 230	skeletal, 39
CH, 101	cut, 324
chasing tactics, 59	associated, 325
Chazelle, B., 177	essential, 324
chord	polygonal, 193
in a polygon, 172	cut-edge, 143
in a visibility map, 155	cycle, 289
of a function, 55	approximate, 195
closure, 50	
collinearity, 100	de Beaune, F., 59
complexity	decision tree, binary, 134, 136, 147
computational, 12	Descartes, R., 17
linear, 13	destination, 33
of shape, 129	determinant, 101
time, 12	Dijkstra's algorithm, 25
component, 50	Dijkstra, E.W., 25
compound, of polynomials, 69	dilation, 276, 344
computer	disk, 99
abstract, 12	distance
normal sequential, 12	Euclidean, 17, 28
conformality, 156	forest, 18
constraint, partitioning, 131	Minkowski, 17
contact, 326	distance measure, Minkowski, 18
convergence, 44	Dror, M., 323, 343
multigrid, 57	DSS, 301
of a path, 69	
of an RBA, 64	edge, 230
of pursuit paths, 61	critical, 230
speed of, 57	in a cell, 81
convexity, 98	in a graph, 23
coordinate system	interior, 173
Cartesian, 27	maximal and minimal, of a polygon, 141
right-hand, 27	Efrat, A., 323, 343
Copenhagen, 308	ellipse, 352
corridor, 192	end-angle, 241
cover, of a cavity, 102	endoscopy, 225
cross product, of sets, 73	equivalence
cube, 194, 204	asymptotic, 34
cube-arc	topological, 51, 192
(2,3), 2- and 3-, 275	ESP, 19, 31

generic, 81	Guanajuato, 10
in a corridor, 192	-
in a simple polyhedron, 192	half plane, 99
on the surface of a polyhedron, 192	Halmos, P. R., 14
ESP problem	Heron of Alexandria, 45
fixed, 61	Hoare, C. A. R, 59, 107
fixed line-segment, in 3D, 65	hole, 98
floating, 62	in a polygon, 130
general 3D, 40	homeomorphism, 51
Euclid of Alexandria, 16, 20	hull, convex, 98, 100
Euclidean shortest path, 171	hull, convex, relative to outer polygon, 115
event, closure and vertex, 160	1 76
	iff, 14
face, 134, 230	initialization, of an RBA, 63-65, 69, 74
critical, 272	inner-angle, 241
of a partitioning, 130	interior, 29, 48, 50
of a polyhedron, 29	interval
first end point of $e$ , 255	closed, 48
free space	monotonous, 73
generic ESP, 81	open, 48
frontier, 29, 48, 50	iterations, number of, 68, 92
of a band, 195	,,,
function	Jordan, C., 28
characteristic, 101	, , ,
concave, 47	Klette, G., 39, 102, 127
continuous, 51, 53, 70, 73	
convex, 47	La Cumbrecita, 96
Fundamental Theorem of Algebra, 15	length, 17, 52
funnel, 173	of a curve, 52
,	of a path, 19, 20
Galois, È., 16, 288	limit, 44
game, 62, 129	line
Gauss, C. F., 15, 39	critical, 242
geodesic, 23, 208	oriented, 99
geometry	line segments, non-disjoint, 75
digital, 117	linear, $\kappa$ -, 68
Euclidean, 16	Listing, J. B., 30, 131
good prime, 289	loop, 28
Graham, R., 105	Lubiw, A., 323, 343
graph, 23	
cell visibility weighted, 82	map, shortest-path, 161
cell visibility weighted, for a point, 83	maximal run of parallel critical edges, 255
dual, 132, 156, 175, 176, 194	measure, 11
weighted, 23	Melkman, A., 112
grid, 230	method
Hippodamian, 22	n-section, 53
regular orthogonal, 17	binary search, 54
grid cube, 230	Chazelle triangulation, 89, 155
group	fast marching, 225
Abelian, 289	for handling degenerate cases, 77
Galois, 289	Newton-Raphson, 54, 56
normal sub-, 290	metric, 18
solvable, 290	Euclidean, 28
symmetric, 290	middle-angle, 241
- ·	<b>C</b> .

minimum, global and local, 72	polygon, 28
Minkowski addition, 344	approximate minimum-length pseudo, 273
Minkowski, H., 17	critical, 212
Mitchell, J. S. B., 161, 323, 343	inner, 141
MLA, 276	isothetic, 110
MLP, 118, 229–231, 301	minimum-length, 118, 229
MLPP, 273	minimum-length pseudo, 273
MPP, 115	minimum-perimeter, 115
	monotone, 142
neighborhood, $\varepsilon$ -, 48	simple, 28, 52, 130
Newton, I., 52, 54	strictly monotone, 126, 142
node, 23	up- and down-, 141
in a graph, 23	visible from the outside, 109
non-existence, 206	polygonal cut, 193
non-trivial vertex, 273	polygonal cuts, sequence of, 193
NP, complete and hard, 36, 222, 226, 311	polygone, monotone, 126
number	polygons, non-overlapping, 191
complex, 15	polyhedron, 29, 191
natural, 13	Listing, 131
rational, 12, 289	Schönhardt, 217, 221
, , ,	simple, 29, 192, 212
obstacle, 19, 31, 192	toroidal, 131
operation, basic, 12	type-1 and type-2, 212
optimization, local, for an RBA, 64	polyline
Option 3, revised, 272	downward visible, 193
orientation	simple, 112
clockwise, 273	upward visible, 193
counter-clockwise, 273	polynomial, 15
origin, of a coordinate system, 27	convex, 57
origin, or a coordinate system, 2,	unsolvable, 16
Paneum, 20	principle
Paramesvara, V., 56	binary search, 54
parameter, free, 14	brute-force, 14
partitioning, 129, 130	divide-and-conquer, 107
parts cutting, 33	throw-away, 14, 104
path, 19	problem
4- and 8-, 117	continuos Dijkstra, 158
Euclidean shortest, 19	ESP, 32
in a tree, 133	general surface ESP, 206
polygonal, 103	obstacle avoidance, 192
pursuit, 59	parts-cutting, 310
shortest, in a graph, 23	safari route, 343
total weight of a, 23	touring ellipses, 352
visits a polygon, 310	touring-polygons, 309
pattern recognition, 129	travelling salesman, 311
permutation, 289	unsolvable, 15
Perry, S., 93	watchman route, 323
pheromones, 96	zookeeper route, 344
plane, 27	problem size, 13
pocket, 324	projection, 242
point	Ptolemaic dynasty, 23
extreme, 104	puzzle, triangle, 129
visible, 327	
points, collinear, 100	query point, 135
r · · · · · · · · · · · · · · · · · · ·	1 A L

redicals solvable by 15	saguanaa 20
radicals, solvable by, 15	sequence, 20
Raphson, J., 54	Cauchy, 45
RBA, 63	Serapeum, 20
edge-based, for cube-curves, 281	set
face-based, for cube-curves, 282	bounded, 49, 98
for a sequence of simple polygons, 314	closed, 48, 49
for an approximate AMLPP, 280	compact, 49
for an approximate MLA, 280	convex, 98
for convex hull calculation, 108	open, 48, 49
for convex hull of a simple polygon, 114	topologically connected, 50
for ESP based on trapezoidal decomposition,	shape complexity, 129
180	shape factor, 126
for fixed line-segment ESP problem in 3D,	Sharir, M., 62
77	shift distance, 141
for floating WRP, 333	shortest path
for polygonal cuts, 197	in a simple polygon, 33
for safari route, 348	on the surface of a simple polyhedron, 34
for surface ESP, 203	shortest-path problem, of graph theory, 25
for the fixed TPP, 315	signal tree, 161
for the floating TPP, 316	simple polygon, 171
for touring ellipses, 353	singleton, 102, 130
for type-1 polyhedrons, 218	skeleton, 39
for type-2 polyhedron, 220	Sklansky test, 107
for WRP with start point, 332	Sklansky, J., 107
for zookeeper route, 351	solution
generic, 86	approximate, 16
generic for 2.5D case, 207	exact, 16, 33
generic for 3D case, 225, 300	for an ESP problem, 33
original, 234, 237, 254, 272	interval, 72
revised, 272	isolated, 72
RCH, 120	source, 33
rectangle	space
<i>q</i> -, 213	3D, 27
axis-aligned, 214	metric, 28
rectangles, stacked, 34	SPM, 161
relative convex hull, 115	SRP condition, 345
resolution, of decomposition, 81	star unfolding, 208
result, accurate, 66	step step
robotics, 36	of a pursuit path, 61
root, 15	of an RBA, 62
isolated, 72	step set, 218
root of 2, 45	stop criterion, 43, 93
Rosenfeld, A., 18	of an RBA, 64
rubberband, 93	strip, horizontal and vertical, 213
rubberband algorithm, original, 235	subarc, 275
rabberband argoriumi, originar, 255	submap, 155
scale, geometric, 20	subsurface, 194
Schorr, A., 62	sweep space, 160
search, breadth-first, 23	5 поср врасс, 100
	Ton V 242
search domain, 31	Tan, X., 343
search space, 81	tangent calculation, 346 Tee, G., 55
second end point of e, 255	
segment, visible, 328	theorem, mean-value, 56, 233
Seidel, R., 139	theory, Galois, 16

vertex, 19, 230
concave, 107, 324
concave or convex, 107
convex, 107, 324
extreme, 104
funnel, 173
reflex, 324
trivial, 273
visibility, 109, 193, 327
for a polygon, 29
for a polyhedron, 30
of cells, 82
visibility graph
indirect, 89
visibility map, 155
visit
for the first time, 50
of a set by a path, 50
volume, 101
wavelet, 158
Weierstrass, K. T. W., 45
weight
of a face, 155
of an edge in a graph, 23
world, cuboidal, 229, 230
WRP, 323
fixed, 324
плец, 32-т
zoro of a function 52
zero, of a function, 53
ZRP condition, 345